## CITY UNIVERSITY OF HONG KONG

## 香港城市大學

## Alignment and Operation for Microassembly based on Microscopic Vision and Force Information

基於顯微視覺與力信息的微裝配對準與操作

**Submitted to** 

Department of Mechanical and Biomedical Engineering

機械與生物醫學工程系

In Partial Fulfillment of the Requirements For the Degree of Doctor of Philosophy

哲學博士學位

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**May 2017** 

二零一七年五月